L Number	Hits	Search Text	DB	Time stamp
7	16	("4307420" "5387947" "5579026" "5644324" "5682171" "5692061" "5717415" "5737012" "5781165" "5801760" "5886675" "5917460" "5982342" "6064353" "6075557" "6088006") PN	USPAT	2004/01/06 11:20
78	196	1	USPAT; US-PGPUB; EPO; JPO;	2004/01/06 16:22
79	22	345/166.ccls. AND (3D OR (three\$2dimension\$2))	IBM_TDB USPAT; US-PGPUB; EPO; JPO;	2004/01/06 16:47
80	2075	250/208.1.ccls.	IBM_TDB USPAT; US-PGPUB; EPO; JPO;	2004/01/06 16:47
81	65	navigation AND 250/208.1.ccls.	IBM_TDB USPAT; US-PGPUB; EPO; JPO;	2004/01/06 16:4
- ! !	138	three\$2dimensional AND ((sens\$4 OR detect\$4) SAME (movement OR motion)) AND (array NEAR (photo\$2detector OR photo\$2sensor))	USPAT; US-PGPUB; EPO; JPO;	2003/02/26 10:09
-	105	(three\$2dimensional AND ((sens\$4 OR detect\$4) SAME (movement OR motion)) AND (array NEAR (photo\$2detector OR photo\$2sensor))) AND lens	IBM_TDB USPAT; US-PGPUB; EPO; JPO; IBM TDB	2003/02/25 16:54
- !	73	((three\$2dimensional AND ((sens\$4 OR detect\$4) SAME (movement OR motion)) AND (array NEAR (photo\$2detector OR photo\$2sensor))) AND lens) AND digital	USPAT; US-PGPUB; EPO; JPO; IBM TDB	2003/02/25 17:18 i
-	6	(array NEAR7 (perpendicular OR orthogonal)) AND (((three\$2dimensional AND ((sens\$4 OR detect\$4) SAME (movement OR motion)) AND (array NEAR (photo\$2detector	USPAT; US-PGPUB; EPO; JPO;	2003/02/25 17:1
-	295	OR photo\$2sensor))) AND lens) AND digital) ((movement OR motion) NEAR5 (detect\$4 OR sens\$4 OR monitor\$4)) AND 356/28,614,615.ccls.	IBM_TDB USPAT; US-PGPUB; EPO; JPO;	2003/02/26 10:1
- ! !	16	((array NEAR3 (sensor OR detector)) SAME (perpendicular OR "right angle" OR orthogonal)) AND (((movement OR motion) NEAR5 (detect\$4 OR sens\$4 OR monitor\$4)) AND	IBM_TDB USPAT; US-PGPUB; EPO; JPO;	2003/02/26 10:5
-	79	356/28,614,615.ccls.) (three\$2dimension\$3 OR 3-D OR 3D) AND 382/278.ccls.	IBM_TDB USPAT; US-PGPUB; EPO; JPO; IBM TDB	2003/02/26 10:4
· !	0	(far\$2field NEAR3 image) AND ((three\$2dimension\$3 OR 3-D OR 3D) AND 382/278.ccls.)	USPAT; US-PGPUB; EPO; JPO; IBM TDB	2003/08/15 12:0
-	41	(movement OR motion) AND ((three\$2dimension\$3 OR 3-D OR 3D) AND 382/278.ccls.)	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/02/26 10:4
· 	3059	((array NEAR3 (sensor OR detector)) SAME (perpendicular OR "right angle" OR orthogonal))	USPAT; US-PGPUB; EPO; JPO; IBM TDB	2003/02/26 10:5
-	406	((((array NEAR3 (sensor OR detector)) SAME (perpendicular OR "right angle" OR orthogonal))) AND image AND correlation	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/02/26 10:5

Search History 1/6/04 4:57:15 PM Page 1

	1771	(((array NEAR3 (sensor OR detector)) SAME (perpendicular OR "right angle" OR orthogonal))) AND (motion OR movement)	USPAT; US-PGPUB; EPO; JPO;	2003/02/26 10:54
		I	IBM_TDB	
-	286	((((array NEAR3 (sensor OR detector)) SAME (perpendicular OR "right angle" OR orthogonal))) AND image AND	USPAT; US-PGPUB;	2003/02/26 10:55
, 		correlation) AND ((((array NEAR3 (sensor OR detector)) SAME (perpendicular OR "right angle" OR orthogonal))) AND	EPO; JPO; IBM_TDB	
	1	(motion OR movement))	1000_100	!
_	2	(3-D OR 3D OR three\$2dimension\$2) AND	USPAT;	i 2003/02/26 11:58
1	į	((382/102).CCLS.)	i US-PGPUB; , EPO; JPO;	İ
			IBM_TDB	
-	121	(3D OR 3-D OR three\$2dimensional) AND ! 356/622,614,615.ccls.	USPAT; US-PGPUB;	2003/02/26 12:03
!	! :	i	EPO; JPO;	
l I			IBM_TDB	
-	27	(array NEAR3 (detector OR sensor)) AND ((3D OR 3-D OR three\$2dimensional) AND 356/622,614,615.ccls.)	USPAT; US-PGPUB;	2003/02/26 12:03
		tillee@2differisionary AND 330/022,014,013.ccis.y	EPO; JPO;	!
:		 	IBM_TDB	0000100155 15 :=
! -	17	- 5150169.URPN. ("3712716" "3908279" "4036213" "4182316" "4197855" -	USPAT USPAT	2003/02/26 12:47 2003/02/26 12:48
	17	"4303077" "4339954" "4436099" "4447207" "4459109"		2003/02/20 12.40
		. "4485825" "4492236" "4495952" "4528990" "4586515"		
	14340	; "4600012" "4649934").PN. ; (3D OR 3-D OR three\$2dimension\$2) AND image AND	USPAT:	2003/02/26 16:36
	i 17070	digital AND (displacement OR motion OR movement)	US-PGPUB;	
İ			EPO; JPO;	
	72	((3D OR 3-D OR three\$2dimension\$2) AND image AND	IBM_TDB USPAT;	2003/02/26 16:37
	!	digital AND (displacement OR motion OR movement)) AND	US-PGPUB;	:
1	i 	250/221,206.1,206.2,203.4,559.29,559.3,216.ccls.	EPO; JPO;	:
! . -	27	(((3D OR 3-D OR three\$2dimension\$2) AND image AND	i IBM_TDB USPAT:	2003/02/26 16:37
		digital AND (displacement OR motion OR movement)) AND	US-PGPUB;	
		¹ 250/221,206.1,206.2,203.4,559.29,559.3,216.ccls.) AND ₁ ((sensor OR detector) NEAR3 array)	EPO; JPO; IBM TDB	
_	. 3	1 11 12 12 12 12 12 12 12 12 12 12 12 12	_	2003/03/03 10:22
I	'		US-PGPUB;	i
			! EPO; JPO; . IBM_TDB	
-	0	("(motionORmovement)AND(1OR2OR3)").PN.	USPAT;	2003/08/07 15:29
	1	· · · · · · · · · · · · · · · · · · ·	US-PGPUB	
I	İ	İ	EPO; JPO; IBM_TDB	I
!_	581	(motion OR movement) AND (382/278.ccls. OR	USPAT;	2003/08/07 15:30
		((382/154).CCLS.) OR ((382/102).CCLS.))	US-PGPUB;	
	l		EPO; JPO; IBM_TDB	
-	256	array AND ((motion OR movement) AND (382/278.ccls. OR	USPAT;	2003/08/07 15:30
	!	((382/154).CCLS.) OR ((382/102).CCLS.)))	US-PGPUB;	į
]	1.	EPO; JPO; IBM_TDB	1 .
· •	233	(correlat\$3 OR compar\$4) AND (array AND ((motion OR	USPAT;	2003/08/07 15:31
		movement) AND (382/278.ccls. OR ((382/154).CCLS.) OR	US-PGPUB;	
		((382/102).CCLS.))))	EPO; JPO; IBM_TDB	
1_	4768	(stereoscopic OR multi\$directional OR omni\$1directional)	USPAT;	2003/08/15 12:04
1 1	i	AND (motion OR movement) AND (sensor OR detector)	US-PGPUB;	<u> </u> -
	!	·	EPO; JPO; IBM_TDB	
1 _	i		<u> </u>	<u> </u>

	2720	((stereoscopic OR multi\$directional OR omni\$1directional) AND (motion OR movement) AND (sensor OR detector)) AND image	USPAT; US-PGPUB; EPO; JPO;	2003/08/15 12:05
		AND illiage		
	2223	l _(computer OR digital) AND (((stereoscopic OR	IBM_TDB	2002/00/45 42:45
-	. 2223		USPAT;	2003/08/15 12:15
	1	multi\$directional OR omni\$1directional) AND (motion OR	US-PGPUB;	:
İ	į l	movement) AND (sensor OR detector)) AND image)	EPO; JPO;	
İ	0.7	(/aamanataa OD dinital) AND (//at aaaaa i OD	IBM_TDB	
-	97	((computer OR digital) AND (((stereoscopic OR	USPAT;	2003/08/15 12:21
	. [multi\$directional OR omni\$1directional) AND (motion OR	US-PGPUB;	
	i l	movement) AND (sensor OR detector)) AND image)) AND	EPO; JPO;	
		348/42,47,48.ccls.	IBM_TDB	
, -	_	("20030080282").PN.	USPAT;	2003/08/15 12:20
!			US-PGPUB;	İ
İ	1		PPO; JPO;	
	00	/// Andrew the OD district AND /// Andrew COD	IBM_TDB	0000/00/45 40 04
-	33	(((computer OR digital) AND (((stereoscopic OR	USPAT;	2003/08/15 12:21
ļ	i !	multi\$directional OR omni\$1directional) AND (motion OR	US-PGPUB;	
		movement) AND (sensor OR detector)) AND image)) AND	EPO; JPO;	
!	ا م	348/42,47,48.ccls.) AND correlat\$3	IBM_TDB	00000000000
-	1	("6204852").PN.	USPAT;	2003/08/19 12:23
			US-PGPUB;	
1			EPO; JPO;	
		/III	IBM_TDB	0000/10/01 15 15
-	0	("beardsley.in.").PN.	USPAT;	2003/12/31 15:15
1	i .		US-PGPUB;	
1	, i		EPO; JPO;	ļ
!			IBM_TDB	:
1 -	460	beardsley.in.	USPAT;	2003/12/31 15:15
	1 1		US-PGPUB;	
1	!		EPO; JPO;	
	1		IBM_TDB	
! -	i 1 j	beardsley.in. AND 348/\$.ccls.	USPAT;	2003/12/31 15:43
	i		US-PGPUB;	
:	j		EPO; JPO;	 -
İ			IBM_TDB	
-	34	348/\$.ccls. AND (movement ADJ data) AND correlat\$4	USPAT;	2003/12/31 15:43
			US-PGPUB;	
			EPO; JPO;	
ļ		(1000 40501) DV	IBM_TDB	0004/04/05 45 00
_	1 !	("6204852").PN.	USPAT;	2004/01/05 15:29
İ	į		US-PGPUB;	!
i			EPO; JPO;	
		(100.4750.4711) D.1	IBM_TDB	0004/04/05 (5 :=
-	1	("6175647").PN.	USPAT;	2004/01/05 15:42
			US-PGPUB;	
			EPO; JPO;	
			IBM_TDB	. 0004/04/05 45 15
-	226	sato.in. AND vision	USPAT;	2004/01/05 15:43
			US-PGPUB;	: I
!	j		EPO; JPO;	
[IBM_TDB	
-	65	(sato.in. AND vision) AND camera	USPAT;	2004/01/05 15:43
			US-PGPUB;	
1			EPO; JPO;	
	!		IBM_TDB	
-	1468	356/28,614,615.ccls.	USPAT;	2004/01/05 16:38
:			US-PGPUB;	!
I	j	: 	EPO; JPO;	I.
			IBM_TDB	!
! -	753	356/622,614,615.ccls.	USPAT;	2004/01/05 16:38
	j		US-PGPUB;	I
1			EPO; JPO;	
<u>L</u>			IBM_TDB	

	4804	250/221,206.1,206.2,203.4,559.29,559.3,216.ccls.	USPAT;	2004/01/05 16:30
	i 4004	. 250/221,200.1,200.2,205.4,559.29,559.5,210.0015.	US-PGPUB;	2004/01/05 16:38
i .	1		EPO; JPO;	
	1		IBM_TDB	
\ <u>_</u>	382	¹ 382/278.ccls		; 2004/01/05 16:38
! -	!	j	USPAT;	1 2004/01/05 10:38
:	1		US-PGPUB;	j
	1		EPO; JPO;	
1	24	· (200(452) 001 0	IBM_TDB	
-	21	i (396/153).CCLS.	USPAT;	2004/01/05 16:38
i	j		US-PGPUB;	
İ			EPO; JPO;	
1	706	(050/003 4 003 0 003 3 003 6) 001 0	IBM_TDB	0004/04/05 40 00
_	_i 796	(250/203.1,203.2,203.3,203.6).CCLS.	USPAT;	1 2004/01/05 16:38
	1		US-PGPUB;	!
1			EPO; JPO;	
1	0.45	(0.45/000), 0.01.0	IBM_TDB	
i -	215	(345/863).CCLS.	USPAT;	2004/01/05 16:38
	1		US-PGPUB;	i '
!	į		EPO; JPO;	:
		(700/450 450) 00/ 0	IBM_TDB	
-	301	(702/152,153).CCLS.	USPAT;	2004/01/05 16:39
	i		US-PGPUB;	1
	:	!	EPO; JPO;	İ ;
			, IBM_TDB	i .
-	382	382/278.ccls.	USPAT;	2004/01/05 16:39
			US-PGPUB;	
ļ	!	I	EPO; JPO;	i .
!	1		IBM_TDB	'
-	842	(382/154).CCLS.	USPAT;	2004/01/05 16:39
]			US-PGPUB;	
1	1		EPO; JPO;	
ļ	:	·	IBM_TDB	· .
ı -	46	(382/102).CCLS.	USPAT;	2004/01/05 16:39
· i		,	US-PGPUB;	
1			j EPO; JPO;	
1			IBM_TDB	
١_	557	. 348/42,47,48.ccls.	USPAT;	2004/01/05 16:40
!	!		i US-PGPUB;	
ı			EPO; JPO;	
			IBM_TDB	
l <u>-</u>	13	348/42,47,48.ccls. AND (machine NEAR3 vision)	USPAT:	2004/01/05 17:02
l		!	US-PGPUB;	200 0 02
į	!		EPO; JPO;	
: I			IBM_TDB]
_	156	702/153.ccls.	USPAT;	2004/01/05 17:02
	100	, car (cc.,co.)	US-PGPUB;	230 770 1700 17.02
I			EPO; JPO;	<u> </u>
ļ	1		IBM_TDB	į
: -	16	702/153.ccls. AND 345/\$.ccls.	USPAT;	2004/01/05 18:26
-	"	ויסבו זיסט.טויס, באום טייסויש.טויס.		2004/01/00 10.20
	1		US-PGPUB;	!
1]		EPO; JPO;	
1		700/452 colo AND 050/6 colo	IBM_TDB	1 0004/04/05 40:07
; - !	6	702/153.ccls. AND 250/\$.ccls.	USPAT;	2004/01/05 18:27
•			US-PGPUB;	
			EPO; JPO;	
		LIACAND	IBM_TDB	0004/54/07 15 5
-	18	correlat\$5 AND image AND (movement OR motion OR	USPAT;	½ 2004/01/05 18:31
	:	displacement) AND 702/153.ccls.	US-PGPUB;	j
!			EPO; JPO;	;
	1		IBM_TDB	'
¦ -	7850	correlat\$5 AND image AND (movement OR motion OR	USPAT;	2004/01/05 18:31
		displacement) AND "348"	US-PGPUB;	,
I			EPO, JPO;	ļ į

[121	correlat\$5 AND image AND (movement OR motion OR	USPAT;	2004/01/05 18:31
- }			displacement) AND 348/42,47,48.ccls.	US-PGPUB;	
!	i	:		EPO; JPO;	
ij	i	l		IBM TOB	, ,